

Molecular Biotechnology Programme

Uppsala University School of Engineering

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Line inspection robot	
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line. The project to develop the line inspection Research in Västerås, in collaboration with Up inspection problem are presented. The line ins is placed on mechanical design and many deta their motivation. A basic market survey and arrobot are supplied. Keywords	opsala University. Previous solutions to the line pection robot is described and analyzed. Focus alls are given on individual design choices and an estimation of the value of a line inspection he, power distribution, autonomous robot, line-
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